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ear control
systems have
been
developed,
ranging from
digital "fly-by-
wire" flight
control
systems for
aircraft, to
"drive-by-
wire"
automobiles,

to advanced
robotic and
space
systems. As a
result, the
subject of
nonlinear
control is
occupying an
increasingly
important
place in
automatic
control
engineering,
and has
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Robot Analysis
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